

#### Computer Physics Communications 126 (2000) 149-157

# **Computer Physics** Communications

www.elsevier.nl/locate/cpc

# Gaussian wavelet features and their applications for analysis of discretized signals

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#### **Abstract**

Problems of analysis of symmetric, bell-shaped signals registered in a discrete form are considered. Fast and direct methods for their processing are proposed on the basis of vanishing momentum wavelets. Unlike previous works, wavelets of higher order are used extensively in these methods. A new wavelet feature is observed: the permanence of their relative square. It makes possible to choose an optimal scale coefficient that is common for several wavelet-transforms. Numerical simulations show the high accuracy of proposed algorithms comparable with the more laborious methods of a Gaussian fitting to discrete measurements. © 2000 Elsevier Science B.V. All rights reserved.

PACS: 29.85.+c; 02.70.La; 02.70.Hm; 02.70.-c

Keywords: Wavelets; Shift and dilation; Vanishing momentum wavelet; Discretization; Contamination; Superposed signals; Wavelet spectrum

## 1. Introduction

Analysis of signals registered in a discrete form is of importance for data processing in almost any field of experimental physics (see, for example, [1–3]). In many important cases the signal form is symmetrical, bellshaped; in particular, a Gaussian is the most often used approximant due to many physical reasons [1,2,4]. The problem is to evaluate parameters of such a discrete signal, i.e. its position, amplitude and also its half-width in presence of noise, detector uncertainties and influence of other close signals. Rigid timing requirements inherent in contemporary detectors demand to elaborate fast and direct methods for the signal parameter evaluations. Passing through a detector a particle produces an electronic shower. Its bell-shape surface can be approximated by a 2D-Gaussian.

$$N(x, y, A, x_0, y_0) = A \exp\left(-\frac{(x - x_0)^2}{2\sigma_x^2} - \frac{(y - y_0)^2}{2\sigma_y^2}\right),\tag{1}$$

where  $x_0$ ,  $y_0$  are the shower center coordinates, and A is the maximum amplitude. The shower half-widths  $\sigma_X$ ,  $\sigma_Y$ by corresponding axes are supposed to be known for the considered detector domain (or can be calculated from

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<sup>&</sup>lt;sup>1</sup> Supported by RFFI, grant N 97-01-01027, Russian Federation; e-mail: osg@lcta39.jinr.dubna.su.

the known drift velocity). Due to the factorized view of (1) the problem usually is reduced to handle several 1D-Gaussians,

$$g(x; A, x_0) = A \exp\left(-\frac{(x - x_0)^2}{2\sigma^2}\right).$$
 (2)

In such 1D presentation (2) a doublet of two overlapping signals can be approximated as

$$G(x; A, x_1; B, x_2) = A \exp\left(-\frac{(x - x_1)^2}{2\sigma^2}\right) + B \exp\left(-\frac{(x - x_2)^2}{2\sigma^2}\right).$$
 (3)

In the process of registration a signal is to be discretized as a histogram  $\{h_k\}$  on the interval  $(x_{beg}, x_{end})$ ,

$$h_k = \frac{1}{\tau} \int_{x_{k-1}}^{x_k} G(x; A, x_1; B, x_2) dx, \tag{4}$$

where  $x_k = x_{\text{beg}} + k\tau$ , and  $\tau$  is the bin width. Besides, an electronic noise gives a contribution to each histogram bin. Noise values are, in principle, correlated, but according to the earlier study [8] we treat them as independent normal variables with r.m.s. equal up to 10% of the mean amplitude. The weak signals are cut off on the threshold depending on the maximum noise level. However, despite of noise thresholding, some background signals contaminating useful signals can also appear above the threshold level.

Well-known restrictions of Fourier analysis motivated our interest to such a modern signal analysis mean as wavelet-transform [5]. The wavelet transform of a signal f(x) is determined as

$$W_{\psi}(a,b)f = \frac{1}{\sqrt{C_{\psi}}} \int_{-\infty}^{\infty} \frac{1}{\sqrt{|a|}} \psi\left(\frac{b-x}{a}\right) f(x) dx, \tag{5}$$

with the normalizing constant

$$C_{\psi} = 2\pi \int_{-\infty}^{\infty} \frac{|\tilde{\psi}(\omega)|^2}{|\omega|} d\omega < \infty, \tag{6}$$

where  $\tilde{\psi}(\omega)$  is the Fourier transform of the wavelet  $\psi(x)$ . The condition  $C_{\psi} < \infty$  is, at the same time, the condition of the wavelet  $\psi$  existence. It would be true, in particular, if the first n-1 momenta are equal to zero,

$$\int_{-\infty}^{\infty} |x|^m \psi(x) \, dx = 0, \quad 0 \leqslant m < n. \tag{7}$$

According to the Gaussian-like shape of our signals it is natural to choose, as basic wavelets, the family of vanishing momentum wavelets (VMW), since they are generated by a Gaussian distribution function,

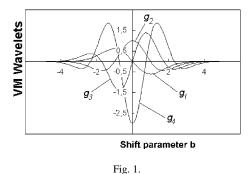
$$g_n(x) = (-1)^{n+1} \frac{d^n}{dx^n} e^{-x^2/2}, \quad n > 0.$$
 (8)

The VMW family is called so because the condition (7) always holds for it.

Two first of VMW are most known [5],

$$g_1(x) = -x e^{-x^2/2}, \qquad g_2(x) = (1 - x^2) e^{-x^2/2}$$

(the second one is also known as "the Mexican hat").



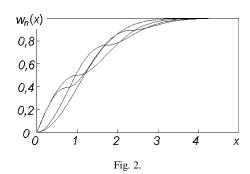


Fig. 1. First four of VMWs.

Fig. 2. Their relative squares.

Nevertheless, we found that the power of the wavelet-analysis can be really extended, if we would use the higher order VMW, in particular,

$$g_3(x) = (3x - x^3) e^{-x^2/2}, g_4(x) = (6x^2 - x^4 - 3) e^{-x^2/2}.$$

The normalizing coefficients of these wavelets  $C_{g_n}$  are  $2\pi(n-1)!$ 

# 2. VMW properties

Between useful VMW properties we stress two, which are related to the VMW derivatives and integrals,

$$\frac{dg_n(x)}{dx} = -g_{n+1}(x), \qquad \int_{x_1}^{x_2} g_n(x) = g_{n-1}(x_1) - g_{n-1}(x_2). \tag{9}$$

The most important VMW property consists in preserving their relative square, which we define as [6]

$$w(x) = \frac{\int_0^x |g_n(x)| \, dx}{\int_0^\infty |g_n(x)| \, dx}.$$
 (10)

The first four of VMWs are shown in Fig. 1. As we have checked, the relative VMW squares calculated for the first ten of VMWs are almost equal forming a specific narrow plait. One can see that clearly in Fig. 2 for the first four VMWs. That is used below in Section 4 for the optimal choice of the dilation parameter.

It is a remarkable fact that the wavelet transformation of a Gaussian (2) looks as the corresponding wavelet. Therefore, the general expression for the *n*th wavelet coefficient has the following form:

$$W_{g_n}(a,b)g = \frac{A\sigma a^{n+1/2}}{\sqrt{(n-1)!}s^{n+1}}g_n\left(\frac{b-x_0}{s}\right),$$

where we denote  $s = \sqrt{a^2 + \sigma^2}$ .

Thus all above-mentioned VMW features are valid also for the Gaussian wavelet-transform. In particular, at the central point  $x = x_0$  coefficients of odd VMWs,  $W_{g_1}(a, x_0)g$  and  $W_{g_3}(a, x_0)g$  equal to zero, while coefficients of even, symmetrical wavelets  $W_{g_2}(a, x_0)g$  and  $W_{g_4}(a, x_0)g$  obtain at this point their maximum (absolute) values,

$$W_{g_2}(a, x_0)g = \frac{A\sigma a^{5/2}}{s^3}, \qquad W_{g_4}(a, x_0)g = -\sqrt{\frac{3}{2}} \frac{A\sigma a^{9/2}}{s^5}.$$
 (11)

To present the wavelet coefficients of a doublet (3) of two Gaussians we use the simplifying normalization,

$$W_n(a,b)g = \frac{W_{g_n}(a,b)g}{w_{g_n}}, \qquad w_{g_n} = \frac{A\sigma a^{n+1/2}}{\sqrt{(n-1)!}s^{n+1}}.$$

Then we obtain

$$W_{g_n}(a,b)G = Ag_n\left(\frac{b-x_1}{s}\right) + Bg_n\left(\frac{b-x_2}{s}\right). \tag{12}$$

### 3. Methods to estimate signal parameters

At this section we derive, first, VMW-based estimates of parameters for "ideal", nondistorted, non-histogrammed signals. These estimates give us the good basis for direct and, therefore, fast algorithms. However, in any real registration process various distortions are brought in. So we have then to study, how much these distortions could influence on the wavelet-transform of such a distorted signal. Only on the basis of this study we can propose recommendations for an optimal choice of shift and dilation VMW parameters, which would guarantee the applicability of proposed algorithms.

Single Gaussian signal. For the single Gaussian signal we can calculate the wavelet transform in a few points and solve the system of corresponding equations. However, applying the ratio of different wavelets we can eliminate the exponent  $e^{-(b-x_0^2)/2(a^2+\sigma^2)}$  and obtain the signal position explicitly. For instance, the ratio  $W_{g_3}(a,b)g/W_{g_1}(a,b)g$  gives

$$x_0 = b \pm \sqrt{(a^2 + \sigma^2) \left[ 3 + \frac{\sqrt{2}(a^2 + \sigma^2)}{a^2} \frac{W_{g_3}(a, b)g}{W_{g_1}(a, b)g} \right]}.$$
 (13)

The true sign in (13) is easy to choose when one would calculate the coefficients  $W_{g_3}(a, b)g$  and  $W_{g_1}(a, b)g$  in a point which is far enough from the supposed signal position.

The amplitude value can be evaluated via the value of the half-width of the signal  $\sigma$  (if known) and one of expressions (11). But in the case when the value of  $\sigma$  is unknown it can be also evaluated using  $W_{g_2}(a, x_0)g/W_{g_4}(a, x_0)g$ ,

$$\sigma^2 = -a^2 \left( 1 + \sqrt{\frac{3}{2}} \frac{W_{g_2}(a, x_0)g}{W_{g_4}(a, x_0)g} \right). \tag{14}$$

Again, the point in which the ratio  $W_{g_2}(a,b)g/W_{g_4}(a,b)g$  is calculated, must be chosen as close to the signal center as possible.

Doublet of close Gaussians. For a doublet of two close signals we can use either

- four first wavelets calculated in one point (method WTS Wavelet Transform System);
- or one of those wavelets (we choose  $g_2$ ) calculated in four different points (method  $g_2$ -WTS).

The corresponding systems of equations are

- for WTS:  $F_n = W_n(a, b)G W_n(a, b)h = 0, n = 1, 2, 3, 4;$
- for  $g_2$ -WTS:  $F_n = W_2(a, b_n)G W_2(a, b_n)h = 0$ , n = 1, 2, 3, 4;

where the nth wavelet coefficient of a histogram h,

$$W_n(a,b)h = \frac{s^{n+1}}{\sqrt{2\pi}\sigma a^{n+1}} \sum_{k=1}^{N} h_k \int_{x_{k-1}}^{x_k} g_n\left(\frac{x-b}{a}\right) dx,$$

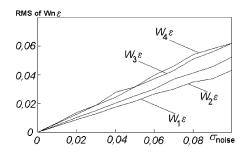


Fig. 3. R.m.s. of the wavelet-transforms  $W_{g_n}(a,0)\varepsilon$  versus the noise level.

is calculated from the source histogram only one time for all iterations.  $g_2$  in the  $g_2$ -WTS method is taken in four following points:  $b_1 = b - h/2$ ,  $b_2 = b + h/2$ ,  $b_3 = b_1 - h$ ,  $b_4 = b_2 + h$  with specially chosen h.

Newton's method is applied to solve these nonlinear systems,

$$\mathbf{D}\Delta \mathbf{X} = \mathbf{F}, \qquad \mathbf{X} = (\mathbf{x}_1, \mathbf{x}_2, \mathbf{A}, \mathbf{B})^{\mathrm{T}}, \qquad \mathbf{F} = (\mathbf{F}_1, \mathbf{F}_2, \mathbf{F}_3, \mathbf{F}_4)^{\mathrm{T}},$$

where **D** is the matrix of partial derivatives of  $F_n$  with respect to components of **X**. The first approach  $\mathbf{X}^{(0)}$  is obtained by a rough estimation of the signal parameters from the source histogram h (see, for example, [8]). The next approach is obtained as  $\mathbf{X}^{(1)} = \mathbf{X}^{(0)} + \Delta \mathbf{X}$  and so on iteratively, unless a wanted accuracy is reached. Calculations of the partial derivatives matrix **D** can be considerably simplified due to the above mentioned VMW-feature (9).

# 4. Optimal choice of shift and dilation parameters

As we assume, the choice of VMW parameters should minimize the influence of various signal distortions. Some results of a study of this influence are described below. Here we focused ourselves especially on the signal distortion due to digitizing and its contamination by additive noise. A histogrammed signal can be considered as

$$\tilde{h}_k = h_k + \varepsilon_k, \qquad k = \overline{1, N},$$
 (15)

where  $h_k$  is the nondistorted signal obtained according to (4) and  $\varepsilon_k$  is the noise addition. Therefore, wavelet-coefficients should also consists of two parts,

$$W_{\varrho_n}(a,b)\tilde{h} = W_{\varrho_n}(a,b)h + W_{\varrho_n}(a,b)\varepsilon. \tag{16}$$

To estimate quantitatively the effect of the second noise component, a numerical experiment was done with 1000 events imitating the contamination of a digitized signal by normally distributed random noise  $\varepsilon$  with the standard deviation  $\sigma_{\text{noise}}$ . The corresponding values of the r.m.s. of  $W_{g_n}(a, 0)\varepsilon$  are shown in Fig. 3.

The nondistorted Gaussian signal with the amplitude A = 1, zero center and  $\sigma = 1.25$  was then histogrammed for different shift values b. The wavelet-transforms  $W_{g_n}(a,b)h$ , n = 1,2,3,4 of this signal as functions of b are depicted in Fig. 1. Comparing them with corresponding r.m.s. values from Fig. 3, one can see that even the maximum wavelet coefficients of noise are two orders of magnitude less than wavelet-coefficients  $W_{g_n}(a,b)h$  for almost all values of b except small, clearly distinctive areas for odd and even wavelets. That gives us the following rule for optimal choosing of the shift parameter b:

- odd wavelets  $g_1$  and  $g_3$  must be calculated in points on signal tails;
- even wavelets g<sub>2</sub> and g<sub>4</sub> must be calculated in points situated as close to the signal center as possible.

The rule to determine the optimal dilation parameter a can be derived from the expression (10) for the invariant relative square w,

$$a = \frac{v}{2}\sqrt{\frac{-1}{2\ln(1-w)}}, \quad v = x_2 - x_1, \quad 0 < w < 1.$$
 (17)

#### 5. Simulations and results

The amazing insensitivity of wavelets to various signal distortions is widely known (see, for example, D. Donoho's article in [5]). However, it was necessary to test more in details the accuracy and efficiency of proposed methods and the dependences of their results on such factors as (i) distance  $d = |x_2 - x_1|/\sigma$  between two components of the doublet signal (3), (ii) noise level and bin shedding, (iii) detector granularity degree. We use Monte Carlo simulations to fulfill this study. The data were simulated as follows. The Gaussian doublet (3) with  $\sigma = 4$  was simulated and histogrammed according to (4) with bin number N and bin-size 1 as it is depicted in Fig. 4(a) (N = 10) and Fig. 4(b) (N = 32). Both peak positions and amplitudes are randomly distributed (an exponential distribution with the mean  $\bar{A}$  was used to generate amplitudes. The single Gaussian signal (2) needed to test the accuracy of the formula (14) was simulated in an analog way. Then discretized signals were distorted by adding to the value in each histogram bin a noise value distributed by the normal or (optionally) by the uniform distribution with  $\sigma_{\text{noise}} = 0.1\bar{A}$ .) Then weak signals with the amplitude less than 10% of  $A_{\text{max}}$  were truncated.

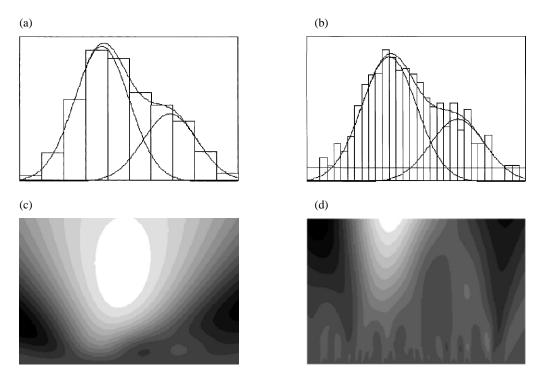


Fig. 4. Effects of various granularity, contamination and thresholding. (a) Histogram of a doublet with low granularity (10 bins). (b) The same signal, but discretized for 32 bins, then noise with 30% amplitude from the signal maximum is added to each histogram bin and cut-off is done on the 10% level. (c) An overall view of the wavelet-spectrum of the discretized signal (a). It stays the same for higher granular, distorted and cutoff signal (b). (d) High frequency part of spectrum for signal (b).

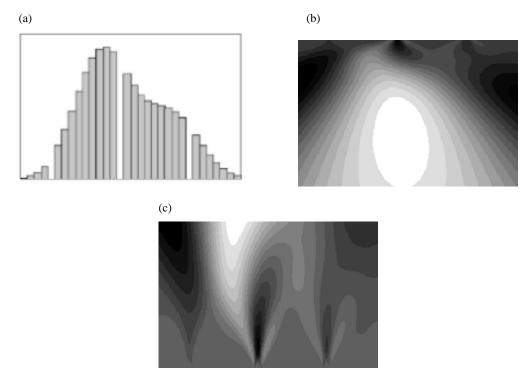
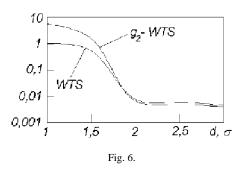


Fig. 5. Bin shedding effect: (a) the source signal is the same as in Fig. 4b (with 10% noise only), but three bins are lost from its histogram; (b) wavelet-spectrum of this distorted signal; (c) high frequency part of spectrum.

Both methods WTS and  $g_2$ -WTS were applied to estimate doublet parameters  $x_1, x_2, A, B$ . Calculating wavelet-coefficients, we set up the dilation parameter a according to (17) with w = 0.9 and  $v = 2|\hat{x}_2 - \hat{x}_1|$ , where  $\hat{x}_1, \hat{x}_2$  are the estimates of position parameters obtained on the current iteration. The maximum number of iteration was set to 10, but it was usually not more than 3–4.

Each point on the dependence plot was obtained by repeating the whole procedure 1000 times. This procedure was implemented as a special WINDOWS-95 software package allowing to vary all simulation parameters and to visualize calculated signals and spectra. Two examples of applying this package to study the influence of various signal distortions on its VMW spectrum are presented in Fig. 4. 2D wavelet-spectra are depicted as gray-level images ranging from black for minimum to white for maximum values. One can clearly see the striking robustness of the VMW to the various signal distortions: only a relatively thin high-frequency layer of the spectrum is violated while the rest of it looks as a spectrum of the nondistorted signal. As one can see in Fig. 5, a similar robustness was developed when three bins of the histogram depicted in Fig. 4(b) were set to zero imitating a malfunctions of data channels.

Results of r.m.s.-error dependence of the signal position estimation on the distance between two signal components determined by WTS and  $g_2$ -WTS methods are shown in Fig. 6, where distances are given in the signal half-width units common for both components. Error values are given in bin-width. The first method has better accuracy when the distance between two peaks in a doublet is less than  $2\sigma$ , although when it approaches  $1\sigma$ -distance, the accuracy decreases considerably for both methods. The relative r.m.s.-error of the estimate  $\hat{\sigma}_g$  of the single Gaussian half-width grows linearly with random noise (in percent of  $\bar{A}$ ) as  $\hat{\sigma}_g = 0.2\sigma_{\text{noise}} + 0.01$ . Dependence of  $\hat{\sigma}_g$  on detector granularity is presented in Fig. 7.



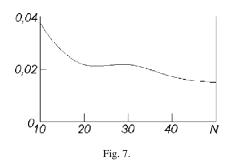


Fig. 6. R.m.s.-error dependences of signal position estimates on the distance between two signal components determined by WTS and g2-WTS methods.

Fig. 7. R.m.s.-error dependences of the single Gaussian half-width estimate on detector granularity (bin number).

As one can see from the given examples, wavelet transform can develop even fine effects of asymmetry and other signal deviations from an ideal Gaussian shape. We do not touch here questions of a quantitative estimations of such deviations, since it would bring us to the different topic related to wavelet series expansion. One can also indicate these deviations by calculating the third and the fourth momenta of the histogrammed signal. We did not also compare here accuracies of the wavelet analysis and the Fourier approach, which is more familiar for experimentalists, since it was already done in [7] for the problem of resolving doublets of close Gaussian discretized signals. As it was shown there in a simplified condition, when the position of one of signals is fixed, the r.m.s. of the wavelet estimation of the distance between both peaks is 20% better than of the Fourier method.

#### 6. Conclusion

The direct formulae are derived to calculate location, amplitude and scale parameters for a single signal and doublets of overlapped signals. Unlike our previous work [7], wavelets of higher order are used extensively in these algorithms. The observed VMW features allows us to choose the optimal wavelet parameters. In particular, the stability of the VMW relative square was found. It makes possible to choose the dilation parameter that is common for several wavelet-transforms. Numerical simulations show the high accuracy of proposed algorithms is comparable with the more laborious methods of a Gaussian fitting to discrete measurements [8]. This study was very facilitated by developing a special user friendly software package for the visualization of simulated signals and their 2D-wavelet spectra for any of the first six Gaussian wavelets.

Approaches published here and in our previous work [6] are already successfully used by some of the JINR physicists [9], although for different purposes.

## Acknowledgements

Authors would like to thank Drs. M. Altaiski and M. Khvastunov for the fruitful discussions and some useful remarks.

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